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1	BRS	L1	788728	(match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) same (attitude or position\$3 or posture\$1 or orientation\$1 or pose\$1 or location\$1)	USPAT	2005/08/03 16:37	
2	BRS	L2	218099	1 same (boundar\$3 or edge\$1 or border\$1 or line\$1)	USPAT	2005/08/03 15:56	
3	BRS	L3	54717	2 same (template\$1 or model\$1 or submodel\$1 or sub-model\$1 or reference\$1 or stored or database or known)	USPAT	2005/08/03 16:01	
4	BRS	L4	972	3 same((high\$3 or low\$3 or small\$3 or big\$4 or maxim\$6 or minm\$6 or increas\$3 or decreas\$3 or increment or decrement) near\$5 (resolution\$1 or size\$1))	USPAT	2005/08/03 16:23	
5	BRS	L5	783	4 same (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3)	USPAT	2005/08/03 14:06	
6	BRS	L6	540	3 same((high\$3 or big\$4 or maxim\$6 or increas\$3 or increment or enlarg\$5) near\$5 (resolution\$1 or size\$1))	USPAT	2005/08/03 14:07	

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7	BRS	L7	565	3 same((low\$3 or small\$3 or minm\$6 or decreas\$3 or decrement) near5 (resolution\$1 or size\$1))	USPAT	2005/08/03 14:09	
8	BRS	L8	106	6 same((low\$3 or small\$3 or minm\$6 or decreas\$3 or decrement) near5 (resolution\$1 or size\$1))	USPAT	2005/08/03 14:09	
9	BRS	L9	249644	((match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) near5 (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3))	USPAT	2005/08/03 14:11	
10	BRS	L10	92	7 same ((match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) near5 (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3))	USPAT	2005/08/03 16:20	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
11	BRS	L11	25	8 same ((match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) near5 (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3))	USPAT	2005/08/03 16:01	
12	BRS	L12	282564	((estimat\$4 or approximat\$4 or determin\$4 or judg\$4 or predict\$4) near3 (attitude or position\$3 or posture\$1 or orientation\$1 or pose\$1 or location\$1))	USPAT	2005/08/03 14:15	
13	BRS	L13	66685	12 same (boundar\$3 or edge\$1 or border\$1 or line\$1)	USPAT	2005/08/03 14:16	
14	BRS	L14	3740	13 same ((correct or accurat\$1 or true or errorless or exact or precise) near3 (attitude or position\$3 or posture\$1 or orientation\$1 or pose\$1 or location\$1))	USPAT	2005/08/03 14:19	
15	BRS	L15	17	13 same ((correct or accurat\$1 or true or errorless or exact or precise) near3 (attitude or pose\$1))	USPAT	2005/08/03 15:55	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
16	IS&R	L16	3250	(382/103,151,195,199,203,209,291,299).CCLS.	USPAT	2005/08/03 15:54	
17	IS&R	L17	477	(348/169).CCLS.	USPAT	2005/08/03 15:54	
18	BRS	L18	5234	((estimat\$4 or approximat\$4 or determin\$3 or comput\$3 or calculat\$4 or evaluat\$4 or correct or accurat\$1 or true or errorless or exact or precise) near\$3 (attitude or pose\$1))	USPAT	2005/08/03 16:18	
19	BRS	L19	724	18 same (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4)	USPAT	2005/08/03 16:11	
20	BRS	L20	129	19 same (boundar\$3 or edge\$1 or border\$1 or line\$1 or outline\$1)	USPAT	2005/08/03 16:19	
21	BRS	L21	3	20 same resolution\$1	USPAT	2005/08/03 15:56	
22	BRS	L22	119	20 same (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometri\$5 or imag\$3)	USPAT	2005/08/03 16:01	
23	BRS	L23	64	22 same (template\$1 or model\$1 or submodel\$1 or sub-model\$1 or reference\$1 or stored or database or known)	USPAT	2005/08/03 16:02	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
24	BRS	L24	9	16 and 23	USPAT	2005/08/03 16:05	
25	BRS	L26	29232	((geometr\$4 or graph\$4) near3 (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4))	USPAT	2005/08/03 16:07	
26	BRS	L27	218	26 same (pose or (orientation adj position\$3) or translation or posture or attitude)	USPAT	2005/08/03 16:09	
27	BRS	L28	5	27 same resolution\$1	USPAT	2005/08/03 16:08	
28	BRS	L29	1575	((refin\$5 or smooth\$4 or clear or clarif\$6) near7 (pose or (orientation adj position\$3) or translation or posture or attitude))	USPAT	2005/08/03 16:20	
29	BRS	L30	66	29 same (resolution\$1 or size\$1)	USPAT	2005/08/03 16:14	
30	BRS	L31	19	30 same (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4)	USPAT	2005/08/03 16:11	
31	BRS	L32	1	16 and 31	USPAT	2005/08/03 16:14	
32	IS&R	L33	219	(358/1.5).CCLS.	USPAT	2005/08/03 16:14	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
33	BRS	L34	96	29 same (resolution\$1 or size\$1 or scal\$3)	USPAT	2005/08/03 16:15	
34	BRS	L35	3	16 and 34	USPAT	2005/08/03 16:15	
35	BRS	L36	20533	(resolution\$1 or size\$1 or scal\$3) same (pose or posture or (position\$3 near1 orientation\$1) or translation)	USPAT	2005/08/03 16:38	
36	BRS	L37	3503	36 same (boundar\$3 or edge\$1 or border\$1 or line\$1 or outline\$1)	USPAT	2005/08/03 16:19	
37	BRS	L38	103	37 same ((match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) near5 (graph\$5 or curv\$5 or polygon\$2 or line\$1 or geometr\$5 or imag\$3))	USPAT	2005/08/03 16:20	
38	BRS	L40	14	38 same((high\$3 or low\$3 or small\$3 or big\$4 or maxim\$6 or minm\$6 or increas\$3 or decreas\$3 or increment or decrement) near5 (resolution\$1 or size\$1 or scal\$3))	USPAT	2005/08/03 16:24	
39	BRS	L41	176	((estimat\$4 or approxim\$4) near3 pose)	USPAT	2005/08/03 16:37	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
40	BRS	L42	71	41 same (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4) same (attitude or position\$3 or posture\$1 or orientation\$1 or pose\$1 or location\$1)	USPAT	2005/08/03 16:38	
41	BRS	L43	71	41 same (match\$4 or correspondence\$1 or similar\$6 or identical\$3 or resembl\$4 or correlat\$4)	USPAT	2005/08/03 16:38	
42	BRS	L44	17	43 same (resolution\$1 or size\$1 or scal\$3)	USPAT	2005/08/03 16:40	


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IEEE JNL IEE Journal or Magazine

IEEE CNF IEEE Conference Proceeding

IEEE CNF IEE Conference Proceeding

IEEE STD IEEE Standard

- ☐ 1. **Comparative study of coarse head pose estimation**
Brown, L.M.; Ying-Li Tian;
Motion and Video Computing, 2002. Proceedings. Workshop on
5-6 Dec. 2002 Page(s):125 - 130
Digital Object Identifier 10.1109/MOTION.2002.1182224
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- ☐ 2. **Operator-theoretic and computational approaches to ill-posed problems in antenna theory**
Nashed, M.;
Antennas and Propagation, IEEE Transactions on [legacy, pre - 1988]
Volume 29, Issue 2, Mar 1981 Page(s):220 - 231
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- ☐ 3. **Using a scale: self-calibration of a robot system with a factor method**
Hanqi Zhuang; Yan Meng;
Robotics and Automation, 2001. Proceedings 2001 ICRA. IEEE International C
Volume 3, 2001 Page(s):2797 - 2803 vol.3
Digital Object Identifier 10.1109/ROBOT.2001.933046
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- ☐ 4. **A scale adaptive method for focusing spectral peaks**
Ribeiro, E.; Hancock, E.R.;
Pattern Recognition, 2000. Proceedings. 15th International Conference on
Volume 3, 3-7 Sept. 2000 Page(s):119 - 122 vol.3
Digital Object Identifier 10.1109/ICPR.2000.903499
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- ☐ 5. **Detection of stellate distortions in mammograms**
Karssemeijer, N.; te Brake, G.M.;
Medical Imaging, IEEE Transactions on
Volume 15, Issue 5, Oct. 1996 Page(s):611 - 619
Digital Object Identifier 10.1109/42.538938
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- ☐ 6. **Recognition and pose estimation of unoccluded three-dimensional objects from a
dimensional perspective view by banks of neural networks**

Khotanzad, A.; Liou, J.J.-H.;
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- ☐ **7. Performance complexity study of several approaches to automatic target from SAR images**
 Aerospace and Electronic Systems, IEEE Transactions on
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 Digital Object Identifier 10.1109/TAES.2002.1008992
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- ☐ **8. Kalman filtering for real-time orientation tracking of handheld microsurgery**
 Wei Tech Ang; Khosla, P.K.; Riviere, C.N.;
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 Volume 3, 28 Sept.-2 Oct. 2004 Page(s):2574 - 2580 vol.3
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- ☐ **9. Semi real-time algorithm for posture estimation of the human face using picture**
 Takahashi, D.; Okamoto, N.;
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- ☐ **10. Object recognition and pose estimation for robotic manipulation using co-occurrence histograms**
 Ekvall, S.; Hoffmann, F.; Kragic, D.;
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- ☐ **11. Absolute head pose estimation from overhead wide-angle cameras**
 Tian, Y.-L.; Brown, L.; Connell, C.; Sharat Pankanti; Arun Hampapur; Senior, A.
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 Digital Object Identifier 10.1109/IVS.2003.1212951
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- ☐ **13. A study on the flexible camera calibration method using a grid type frame line widths**
 Jun-ik Jeong; Seong-Young Moon; Seong-Gu Choi; Do-hwan Rho;
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 Volume 2, 5-7 Aug. 2002 Page(s):1319 - 1324 vol.2
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- 14. Accurate catadioptric calibration for real-time pose estimation in room-size**

- ☐ Aliaga, D.G.;
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Volume 1, 7-14 July 2001 Page(s):127 - 134 vol.1
Digital Object Identifier 10.1109/ICCV.2001.937508
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- ☐ **15. Adapting scale by minimising spectral defocusing for shape from texture**
Ribiero, E.; Hancock, E.R.;
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Digital Object Identifier 10.1109/ICIP.2000.899600
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- ☐ **16. An integrated face detection and recognition system**
Koh, L.H.; Ranganath, S.; Lee, M.W.; Venkatesh, Y.V.;
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- ☐ **17. The MODIS operational geolocation error analysis and reduction method**
Wolfe, R.E.; Nishihama, M.; Fleig, A.J.; Roy, D.P.;
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- ☐ **18. Robust motion estimation using complex wavelets**
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- ☐ **19. High resolution image classification with features from wavelet frames**
Kyoung-Ok Kim; In-Sook Jung; Young-Kyu Yang;
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- ☐ **20. A confidence set approach to mobile robot localization**
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- ☐ **21. Statistical decision theory for mobile robotics: theory and application**
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- ☐ **23. Constraints on quadratic curves under perspective projection**
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- ☐ **24. A microprocessor-based spatial-locating system for use with diagnostic**
Moritz, W.E.; Shreve, P.L.;
Proceedings of the IEEE
Volume 64, Issue 6, June 1976 Page(s):966 - 974
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- ☐ **25. Community dialog technology**
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IEEE CNF IEEE Conference Proceeding

IEEE CNF IEE Conference Proceeding

IEEE STD IEEE Standard

- ☐ 1. **Single and multiscale detection of masses in digital mammograms**
 te Brake, G.M.; Karssemeijer, N.;
 Medical Imaging, IEEE Transactions on
 Volume 18, Issue 7, July 1999 Page(s):628 - 639
 Digital Object Identifier 10.1109/42.790462
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- ☐ 2. **Geometry-based automatic object localization and 3-D pose detection**
 Magnor, M.A.;
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- ☐ 3. **Invariant and perceptually consistent texture mapping for content-based**
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- ☐ 4. **A new fractal zerotree coding for wavelet image**
 Meng Wu; Ahmad, H.O.; Swamy, M.N.S.;
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- ☐ 5. **Reconstruction of myocardial architecture at high resolution using diffus**
 Scollan, D.F.; Holmes, A.A.; Jianyang Zhang; Winslow, R.L.;
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- ☐ 6. **A robust adaptive multi-spectral object detection by using wavelet transform**
Yu, X.; Reed, I.S.; Kraske, W.; Stocker, A.D.;
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- ☐ 7. **A unified recognition and stereo vision system for size assessment of fish**
Naiberg, A.; Little, J.J.;
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- ☐ 8. **An image coding scheme using block prediction of the pyramid subband**
Rinaldo, R.; Calvagno, G.;
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- ☐ 9. **Preparation of MZrO₂/sub 3/ (M=Ba,Sr) buffer layers on surface oxidized Nb by PLD and MOD**
Huhne, R.; Holzapfel, B.; Kursumovic, A.; Evetts, J.E.; Cavallaro, A.; Sandiumi, A.; Puig, T.; Obradors, X.;
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- ☐ 10. **A television display using acoustic deflection and modulation of coherent**
Korpel, A.; Adler, R.; Desmares, P.; Watson, W.;
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Volume 54, Issue 10, Oct. 1966 Page(s):1429 - 1437
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- ☐ 11. **Probability distribution of CW induced currents on randomly oriented surfaces and wires**
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- ☐ 12. **Computer aided impedance matching of an interleaved waveguide phase shifter**
Hsiao, J.;
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- ☐ 13. **Measurement of ferromagnetic phase transformation with Barkhausen noise**
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- ☐ 14. **Sputtered thin magnetic films**

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- ☐ **15. Optical parametric interactions in 3-methyl-4-nitropyridine-1-oxide (POM)**
Zyss, J.; Ledoux, I.; Hierle, R.; Raj, R.; Oudar, J.-L.;
Quantum Electronics, IEEE Journal of
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- ☐ **16. Crystal symmetry effects on nonlinear optical processes in optical wave**
Andrews, R.;
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- ☐ **18. Discrimination of planar shapes using shape matrices**
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- ☐ **19. The semiology of documents**
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- ☐ **20. A frameless stereotaxic operating microscope for neurosurgery**
Friets, E.M.; Strohbehn, J.W.; Hatch, J.F.; Roberts, D.W.;
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- ☐ **21. Partial shape classification using contour matching in distance transform**
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